

UNITED STATES PATENT AND TRADEMARK OFFICE  
**CERTIFICATE OF CORRECTION**

PATENT NO. : 7,092,791 B2  
APPLICATION NO. : 09/265432  
DATED : August 15, 2006  
INVENTOR(S) : Akihiro Terada et al.

Page 1 of 2

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

Title Page Column 2 (Abstract), Line 6, change "moveable" to --movable--.

Title Page Column 2 (Abstract), Line 16, change "the" to --therefore--.

Column 4, Line 13, after "the" delete "a".

Column 5, Line 22, change "axis." to --axis--.

Column 6, Line 21, change "perpendicular." to --perpendicular to the first additional axis 12d and the machining nozzle 2 attached to a distal end of the second additional variable axis 12e in which a direction of irradiating laser beam is directed in a direction perpendicular to the additional rotational axis 12c (the final axis 1 of the movable arm of the robot).--.

Column 6, Line 30, change "12e." to --12e--.

Column 6, Line 50, after "are" delete "is".

Column 7, Line 51, change "restriction-According" to --restriction. According--.

Column 7, Line 61, Change "lob" to --14b--.

Column 8, Line 19, after "the" insert --sixth--.

Column 10, Line 23, change " $y = \sqrt{[(R+r\cos\alpha)(R-r\cos\alpha)]^{1/2} - (R^2 - r^2)^{1/2}}$ " to -- $y = \sqrt{[(R+r\cos\alpha)(R-r\cos\alpha)]^{1/2} - (R^2 - r^2)^{1/2}}$ --.

Column 11, Line 64, change "an" to --can--.

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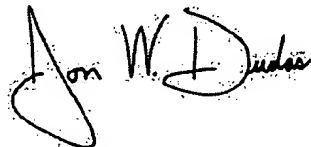
Page 2 of 2

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

Column 12, Line 34, change "moveable" to --movable--.

Signed and Sealed this

Ninth Day of January, 2007

A handwritten signature in black ink, appearing to read "Jon W. Dudas". The signature is stylized with a large initial "J" and a cursive "Dudas".

JON W. DUDAS  
*Director of the United States Patent and Trademark Office*